



# **USER MANUAL**

EVALUATION BOARD FOR WSEN-ISDS

2536030320091

VERSION 1.1

OCTOBER 17, 2024

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# **Revision history**

Manual version	Product version	Notes	Date
1.0	1.0	Initial release of the manual	January 2023
1.1	1.0	<ul> <li>Updated chapter Important notes</li> <li>Updated chapter Legal notice</li> </ul>	October 2024



# **Abbreviations**

Abbreviation	Description
I <sup>2</sup> C	Inter integrated circuit
IMU	Inertial measurement unit
MEMS	Micro electro mechanical system
LSB	Least significant bit
SPI	Serial peripheral interface

## **User manual Evaluation board for WSEN-ISDS**



# **Contents**

1	General description	4				
	1.1 Introduction	4				
	1.2 Pin header compatibility					
2		5				
	2.1 EV-Board in operation	6				
	2.1.1 I <sup>2</sup> C connection (CON1)	6				
	2.1.2 SPI connection (CON2)	7				
	2.1.3 Resistor functionality					
	2.1.4 Through hole connection					
3	EV-Board3.1 Schematic diagram3.2 Layout3.3 Bill of materials	12				
4 Important notes						
5	<ul> <li>Terms of Use for Würth Elektronik eiSos GmbH &amp; Co. KG EV-Boards, evaluation kits and evaluation modules</li> <li>Legal notice</li> </ul>					
6						
7	7 License terms for Würth Elektronik eiSos GmbH & Co. KG sensor product software and source code					



## 1 General description

## 1.1 Introduction

The EV-Board of the IMU (Inertial Measurement Unit) 6 axis sensor provides an opportunity to verify the sensor performance and develop a prototype using an extension board e.g. Sensor shield for Arduino (Part No. 2501000101291). It can be directly plugged to sensor shield using the mounted I<sup>2</sup>C and SPI interface pins. The EV-Board can also be mounted on a bread board using through hole pin header connections. The 6 axis IMU sensor (Part No: 2536030320091) is a 16-bit digital ultra-low-power and high-performance MEMS sensor. It includes 3 axis linear accelerometer and 3 axis gyroscope. The digital host interface offers either I<sup>2</sup>C or SPI to communicate with the sensor.

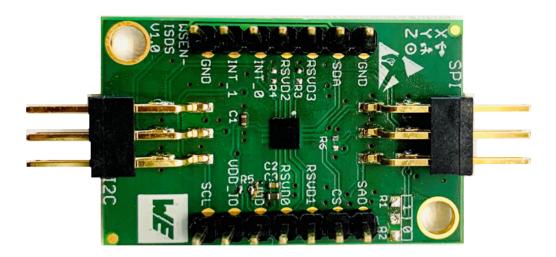


Figure 1: EV-Board for the IMU 6 axis sensor

## 1.2 Pin header compatibility

6-pin right angle headers mounted on this EV-Board can be directly plugged into the sensor shield for Arduino or sensor FeatherWing. This serves a plug-and-play solution to quickly take the EV-Board into operation.



Sensor shield for Arduino is a stackable extension board for Arduino UNO and DUE to connect the sensor EV-Boards. More information can be found on our *website*.



## 2 Functional description

The acceleration sensor EV-Board supports the standard I<sup>2</sup>C and SPI communication interface. By default, I<sup>2</sup>C communication interface is enabled in the EV-Board.

- A positive supply voltage is applied to the sensor through VDD pin and I/O supply voltage for digital interface through VDD\_IO pin. The VDD and VDD\_IO pins on the board are connected together using 0 Ω resistor R6.
- The I<sup>2</sup>C communication is enabled by connecting *CS* pin to *VDD\_IO*. The *CS* pin is connected to *VDD IO* using 100 k $\Omega$  resistor R5.
- The 7-bit slave address of the acceleration sensor is 110101xb. LSB of the 7-bit slave address can be modified using the *SAO* pin.

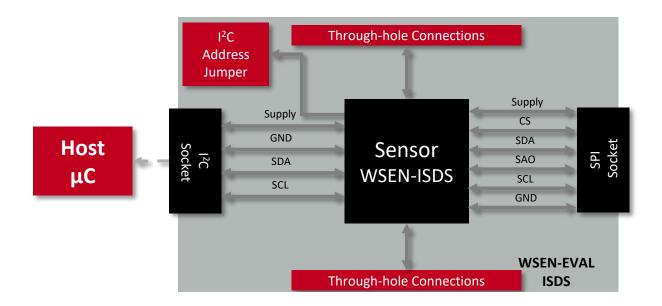


Figure 2: Block diagram of the EV-Board



By default the 7-bit slave address of the acceleration sensor on the EV-Board is 1101011b (0x6B). i.e. SAO pin of the sensor is connected to  $VDD\_IO$  using 100 k $\Omega$  resistor ADR.



The 7-bit slave address of the acceleration sensor can be changed to 1101010b (0x6A) by removing 100 k $\Omega$  resistor ADR from '1' part and mounting 0  $\Omega$  resistor on the '0' part of the EV-Board. i.e. *SAO* pin is connected to *GND*.





Please refer to the data sheet and user manual of the IMU 6 axis sensor (Part No: 2536030320001) for more information about the electrical properties.

## 2.1 EV-Board in operation

## 2.1.1 I<sup>2</sup>C connection (CON1)

The pinning of connector CON1 provides I<sup>2</sup>C communication interface, which fits directly to the *sensor shield for Arduino* and *sensor FeatherWing* as mentioned in section 1.2. The I<sup>2</sup>C communication interface is the default state of the board.

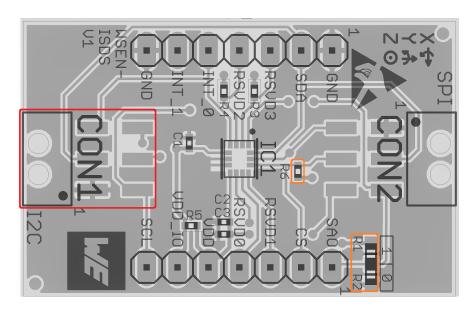
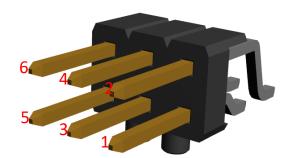


Figure 3: I<sup>2</sup>C Pin header connection to the external boards



Pin No	I <sup>2</sup> C Pins (CON1)
1	GND
2	SCL
3	SDA
4	INT_1
5	INT_0
6	VDD

Table 1: I<sup>2</sup>C Pin header





R6 shall be populated to enable I<sup>2</sup>C communication.



Either R1 or R2 shall be populated to define the LSB of sensor's address.



Connecting the sensor EV-Board to the sensor FeatherWing using I<sup>2</sup>C or SPI interface pins will disable INT\_0 and INT\_1 interrupt pin functions.

## 2.1.2 SPI connection (CON2)

The pinning of connector CON2 provides SPI communication interface, which fits directly to the sensor shield for Arduino and sensor FeatherWing as mentioned in section 1.2.

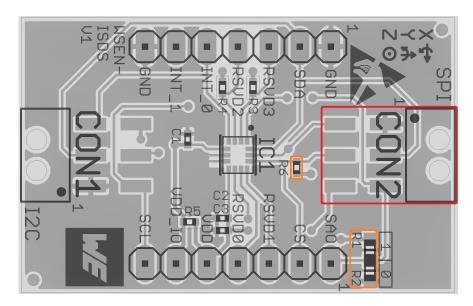
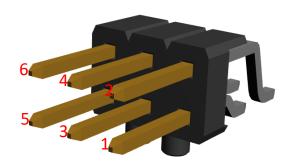


Figure 4: SPI Pin header connection





Pin No	SPI Pins (CON2)
1	GND
2	SCL
3	SDA (MOSI)
4	CS
5	SAO (MISO)
6	VDD

Table 2: SPI Pin header to external boards



SPI communication is enabled by removing the R1, R2, and R6 resistors.

## 2.1.3 Resistor functionality

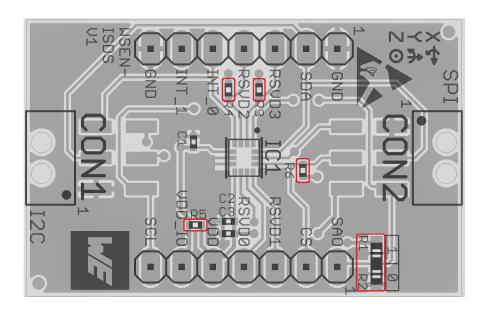


Figure 5: Resistor functionality



Resistor	Description
R1, R2	R1 is by default populated. <i>SAO</i> is connected to the <i>VDD_IO</i> , therefore the I <sup>2</sup> C address of sensor is 1101011b. If R2 is assembled the the I <sup>2</sup> C address of sensor is 1101010b.
R3, R4	Reserved functionality. Do not remove.
R5	VDD and VDD_IO pins are connected together.
R6	I <sup>2</sup> C enabled by default. <i>CS</i> is connected to <i>VDD_IO</i> . To enable SPI communication, remove R1, R2 and R6 resistors.

Table 3: Functionality of the resistors on the EV-Board



Check in your configuration, if the resistors R1, R2 and R6 have to be removed before connecting the EV-Board to a processor.

## 2.1.4 Through hole connection

Through hole pin headers connection gives direct access to each sensor pin. Please refer to table 4 and 5 for the pin description of P1 and P2 respectively.

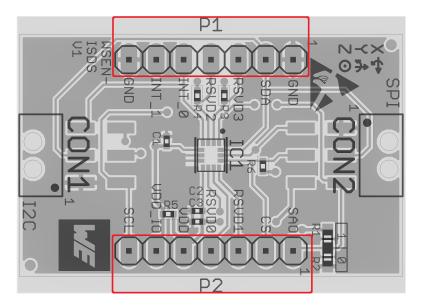


Figure 6: Through hole connection P1 and P2



Pin No.	EV-Board pins	Description	Input/Output
1	GND	Negative supply voltage	Supply
2	SDA	I <sup>2</sup> C serial data, SPI serial data input	Input/Output
3	RSVD3	Reserve functionality. Corresponds to sensor's pin 2	Input/Output
4	RSVD2	Reserve functionality. Corresponds to sensor's pin 3	Input/Output
5	INT_0	Interrupt pin 0	Output
6	INT_1	Interrupt pin 1	Output
7	GND	Negative supply voltage	Supply

Table 4: Pin description of P1

Pin No.	EV-Board pins	Description	Input/Output
1	SAO	I <sup>2</sup> C device address selection, SPI serial data output	Input/output
2	CS	I <sup>2</sup> C enable/disable, SPI chip select	Input
3	RSVD1	Reserved functionality. Corresponds to sensor's pin 11	Input/Output
4	RSVD0	Reserved functionality. Corresponds to sensor's pin 10	Input/Output
5	VDD	Positive supply voltage	Supply
6	VDD_IO	Positive supply voltage for I/O pins	Supply
7	SCL	I <sup>2</sup> C/SPI serial clock	Input

Table 5: Pin description of P2



## 3 EV-Board

## 3.1 Schematic diagram

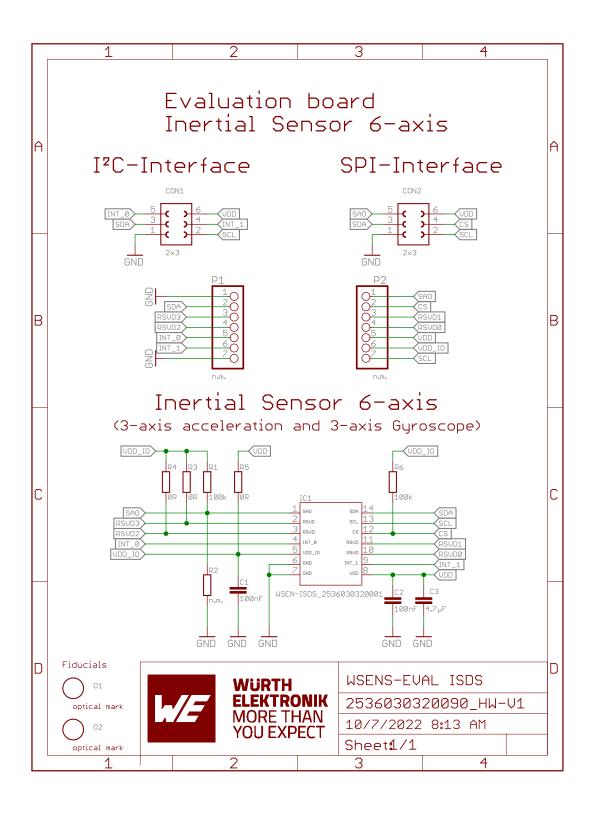


Figure 7: Schematic diagram



## 3.2 Layout

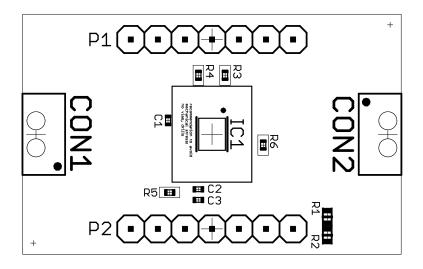
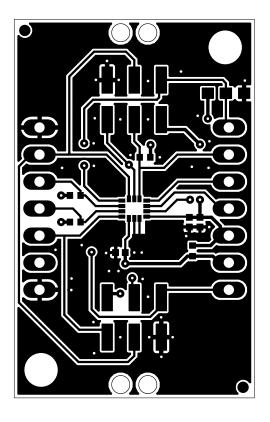


Figure 8: Assembly diagram



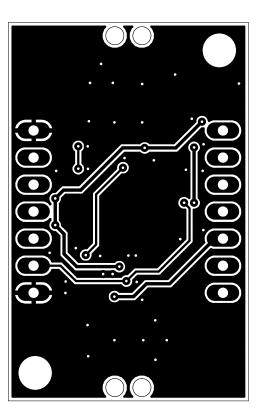


Figure 9: Top (left) and bottom (right) layers



## 3.3 Bill of materials

Part	Value	Pack	Manufacturer	NR
C1	100 nF	0402	Würth Elektronik eiSos	885012205037
C2	100 nF	0402	Würth Elektronik eiSos	885012205037
C3	4.7 μF	0402	Würth Elektronik eiSos	885012105008
CON1	2x3	THT	Würth Elektronik eiSos	610106249121
CON2	2x3	THT	Würth Elektronik eiSos	610106249121
IC1	WSEN-ISDS	SMT	Würth Elektronik eiSos	2536030320001
P1	n.m.	SMT	n.m.	n.m.
P2	n.m.	SMT	n.m.	n.m.
R1	100 kΩ	0603	Yageo	RC0603FR-10100KL
R2	n.m.	SMT	n.m.	n.m.
R3	0 Ω	0402	Yageo	RC0402FR-070RL
R4	0 Ω	0402	Yageo	RC0402FR-070RL
R5	0 Ω	0402	Yageo	RC0402FR-070RL
R6	100 kΩ	0402	Yageo	RC0402FR-07100KL

Table 6: Bill of materials

#### User manual Evaluation board for WSEN-ISDS



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#### User manual Evaluation board for WSEN-ISDS



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- · Do not touch the EVB while it is live.
- The EVB must be fully assembled and all devices to be tested must be connected before voltage is applied to the EVB.
- The EVB should never be left unattended during operation.
- · Capacitors must be completely discharged. The capacitors must be actively discharged using a suitable resistor.

#### Protection against static electricity

Use the unpackaged product only in ESD protected areas. Wear the ESD personal protective equipment prescribed for these areas. Ground all conductive components, including personnel, as prescribed in ESD protected areas. Ensure that the product is only used by trained personnel.

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The EVB is not a finished product and is not intended for general use by the consumer. The EVB is intended exclusively for use in the evaluation of WE components in the lab or in development environments by highly qualified technicians or engineers, familiar with the risks involved in handling electrical or mechanical components, systems and subsystems. The use of the EVB is your full and independent responsibility. The EVB is expressly not intended to be installed in a terminal device or to be part of a terminal device in whole or in part. WE reserves the right, at its own discretion, to make corrections, improvements, adjustments or other changes to the EVB or to discontinue the EVB. The EVB is not intended for use in devices and applications for which a higher safety and reliability standard is prescribed. It is also not approved for use in safety-relevant applications or where personal injury or fatal consequences must be expected in the event of failure.

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#### User manual Evaluation board for WSEN-ISDS



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Miscellaneous

## **User manual Evaluation board for WSEN-ISDS**



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## **User manual Evaluation board for WSEN-ISDS**



# **List of Figures**

1	EV-Board for the IMU 6 axis sensor	4
2	Block diagram of the EV-Board	
3	I <sup>2</sup> C Pin header connection to the external boards	
4	SPI Pin header connection	7
5	Resistor functionality	8
6	Through hole connection P1 and P2	
7	Schematic diagram	
8	Assembly diagram	2
9	Top (left) and bottom (right) layers	2
.ist	of Tables	
1	I <sup>2</sup> C Pin header	6
2	SPI Pin header to external boards	8
3	Functionality of the resistors on the EV-Board	9
4	Pin description of P1	0
5	Pin description of P2	0
6	Rill of materials	3



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